

FLEET MANAGEMENT SYSTEM FOR AN ADVANCED HELICOPTER PLATFORM - DESIGN & DEVELOPMENT REQUIREMENTS

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Abstract

The investigated advanced defence helicopter fleet will be undergoing a major acquisition process including upgrade under a 20+ year strategic plan. This program develops aims to rationalise the number of helicopter operated, simplify operational requirements and reduce through life support costs. The helicopter fleet presently comprises of nine helicopter types, to be grouped to three to four fundamental types. A fleet management methodology needs to be developed and modelled for each fundamental type of helicopter. This research will assess current practices in aerospace technology management of military aircraft fleets and establish requirements for both, civil and military rotaryplatforms and design a specific methodology for the fundamental Multi-Role Helicopter (MRH, NH-90) of the defence forces. The outcome will be a technology management methodology, demonstrated through simulation for application on the MRH.

The research studied the present and future fleet of the operators to establish the helicopter fleet needs, operational doctrines and logistic support requirements. It adopts a systems approach to develop the fleet management methodology for application on the MRH platform within a technology management environment. The fleet management system was considered as the total system and the MRH and its support infrastructure were located at the lower levels of the hierarchy. Establishing a systems concept of the various hierarchy levels

identified the attributes and relationships of the system components.

Presently, the research is analysing the FMS technology status of current civil and military rotorcraft platforms for stipulating the design requirements of a FMS methodology and simulation model. The methodology under development will be subsequently integrated into a software tool (task in progress) to provide parameters, helicopter fleet availability infrastructure support requirements and assist maintenance planning increase tooperational effectiveness. A system dynamic model is designed and developed to provide quantitative results. These results assist in the evaluation & optimisation of the methodology and demonstrate the applicability on the MRH platform.

1 Introduction

In the civil and military sectors, rotary wing technology provides major benefits to the community and the industry. It has proven its capabilities in service for emergency and military support over the years. Rotary wing platforms cover a variety of missions, conducting passenger and emergency transport, search & rescue tasks, heavy lift duties and military roles. Defence forces worldwide operate and maintain large fleets of rotary wing platforms that require advanced management practices for efficient operation and support.

Fleet management addresses the operational and support issue for effective vehicle life-cycle management. It involves tracking & managing usage information and

expenses of a vehicle from need identification to disposal. It is a network of systems that monitors the vehicle's operational status and provides the stipulated support. The goal of fleet management is optimising the availability (reliability & maintainability) of the vehicle at minimum acquisition and support costs to meet the operational readiness benchmark.

Fleet management is based on commercially available tools to track the usage status of aircraft & components and manage the required support. Companies specialising in the development of softwares, customise the tools based on aircraft and fleet types, resulting in several commercially available tools. These tools assist the operators to optimise availability and enhance service life of the vehicle. The tools are limited in usage as it needs customisation for support to a particular fleet. The fleet management software available off-the-shelf and its characteristics are as follows:

- Maintenance and Repair Operations Software: It manages the maintenance activities and associated documentation of aircraft components & parts. The software documentation generates work reports & tasks cards and tracks the parts logistic inventory for support. Regulatory compliance is addressed through airworthiness directive tracking. Commercial features include generation of purchasing orders, and sales & invoicing.
- <u>Scheduling and Reservation Systems</u>: It covers the time schedule of aircraft and equipment for maintenance on missions. Flight reservation systems and ground time scheduling are applied in commercial and general aviation.
- Airline and Airport Software: It provides commercial features for airlines to enhance operational effectiveness. These include planning systems, management and airline controlling. Resource management of personnel and equipment provides the base for timetable generation and flight scheduling.

- <u>Flight Tracking Software</u>: Flight information systems for both, military and civil applications provide data on aircraft positions, air traffic and weather.
- <u>Aviation Manufacturing Software</u>: In support of complex engineering tasks the software assists in the manufacturing design of aircraft & components.
- Aviation Leasing Software: Management of leasing aircraft and components is addressed through portfolio and contract management software. It covers commercial and technical documentation of leasing assets.

The above off-the-shelf software covers aspects of operations and support. It is limited in application for life-cycle management of the fleet [1]. It is designed for general and commercial aviation, with limited flexibility for customisation to military applications. Military aircraft life-cycles exceed the service life of commercial aircraft due to lower usage and extended life through mid-life upgrades to enhance mission capability. This requires builtflexibility in the technology insertion management system. The different composition of operating and support costs between fixed- & rotary-wing aviation and its support structure requires a customised alternative for military helicopter applications for overall life-cycle management and support. Research in Fleet Management investigates issues related to increase the average age of military aircraft fleets [2], and the operational acquisition costs faced by operators. The research aims to extend the service life [3] of the airframes to enhance operational effectiveness [4] and predict fleet reliability [5]. To address issues of aircraft scheduling, performance and cost management; probabilistic approaches [6, 7] and statistical models [8] are being considered; including single or multiple type fleets to optimise maintenance and training procedures [9].

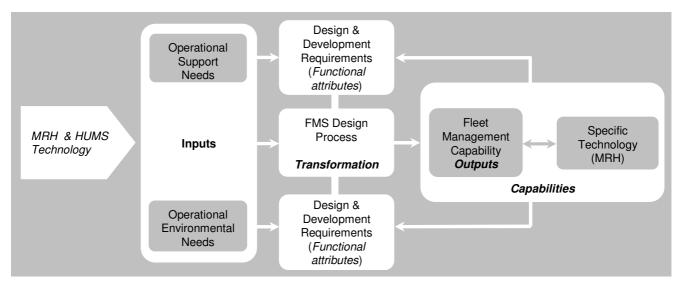


Fig.1. Systems Perspective of FMS for Holistic Analysis

2 Systems Perspective – Fleet Management

A system is composed of components, attributes, and relationships. The components are also referred as subsystems. The attributes the functional characteristics of the components designating functional the requirements in the design of a system [10]. Relationships are the inter and relationships between components and attributes and provides the synergy. The purpose of the system is achieved by the system's process by transforming the inputs into desired outputs [10]. A system may be part of a larger system in a hierarchy, and its components may be referred as a subsystem.

The system may be referred as a total system, at any level governed by the system / component under study. The system structure comprises of the components, its attributes [11, 12], the inputs from the environment into the system and the output to the environment. The Fleet Management System (FMS) will be analysed in this context from a systems perspective for a holistic analysis.

2.1 System Configuration

The FMS is considered in a typical inputprocess-output system configuration. The FMS is to be developed for the MRH, hence the "support needs" for the operation of the MRH fleet needs to be considered. These support needs are to be the inputs of the FMS process. The support needs will comprise of the "operational support needs" for the designated roles and missions of the MRH. It will also comprise of the "operational environmental needs" on the foreseen spectrum of conditions in which the MRH will need to operate. The MRH systems technology, specifically the Health & Usage Monitoring Systems (HUMS) on-board and off-board, will form an additional critical input dimension to the FMS process.

The analysis of the support needs to the FMS process will stipulate the design and development requirements of the FMS. The output of the process will be the fleet management capability. The FMS in the input-process-output context from a systems perspective provides the base for a holistic analysis to develop the FMS for application on a specific technology – the MRH. The systems perspective of the FMS in an input-process-output configuration is presented in Fig.1.

2.2 System Hierarchy

The system hierarchy of the FMS will need to be developed to identify its subsystems and components for the development of the system structure at each level, for further analysis. The system structure will stipulate the 'Inputs', 'Process' and 'Outputs' at various levels of the

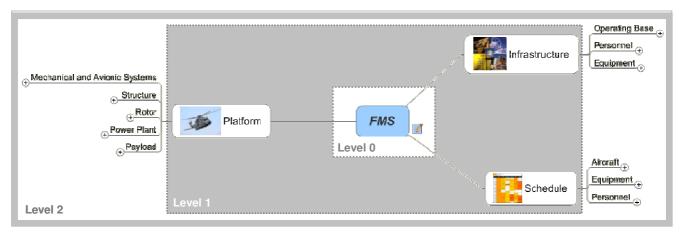


Fig.2. System Hierarchy – Levels 1 and 2

hierarchy, for the FMS to address in providing the required support to the MRH.

2.2.1 Level 0 to 1

The FMS is considered as the total system at Level '0' of the system hierarchy. The MRH Platform is a subsystem of the FMS and a component at Level 1 of the FMS hierarchy. subsystems needed to provide The other support will comprise of the operational 'Infrastructure' needed to support and the schedule pattern in which the 'stipulated' support will be provided. Thus the subsystems / components at Level 2 of the hierarchy are 'Infrastructure' 'Platform', and 'Schedules' (Fig. 2).

2.2.2 Level 2

The development of the Level 2 hierarchy requires a further detailed analysis of the Level 1 subsystems (Platform, Infrastructure and Schedule). Analysis of the Platform will need an understanding of the various key assemblies that contribute to the operation of the platform. Infrastructure components need to cover from personnel to the operating bases. The Schedule subsystems needs to be in-order to those stipulated in real-time for both personnel and platform activities.

• Platform: The platform encompasses the housing for various assemblies / components, propulsive power and components that contribute to the mission accomplishment. The housing is the airframe structure and the propulsive power is provided by the engines and the

- rotor system. The systems that contribute to the mission accomplishment are the mission systems payload governed by the role and mission of the platform. Thus the key components of the platform system are 'Structure', 'Power Plant', 'Rotor', 'Mechanical & Avionic Systems' and 'Payload' [13].
- Infrastructure: It comprises of the systems required for rotary-wing operations and support. The operating bases are airbases on-ground and onships. At each of these the personnel to support operate and the aircraft comprises of: aircrews, maintenance crews. ground personnel and administrative staff. Equipment for operations support include and maintenance and testing, fuel ordnance and ground support equipment including availability of spare parts & personnel. Thus the three subsystems of Infrastructure are 'Operating Bases', 'Personnel', and 'Equipment'.
- Schedule: Schedule comprises of the operations and support activities related to planning and timing of personnel, aircraft, and equipment. At the base, these consist of the allocation of aircraft and maintenance crews to servicings and inspections including upgrades and modifications for maximum availability of aircraft. Scheduling also includes training for both, air crews and ground

Components	Platform	Infrastructure	Schedule
	Troops / Cargo / Equipment Transportation	Training	Training
	Tactical Support	Maintenance Support	Maintenance Support
A ttuibutas	Survivability	-	-
Attributes	Training	-	-
	Med / Cas Evac	-	-
	Armed Reconnaissance & Surveillance	-	-

Tab.1. Components and Attributes based on Operational Support Needs

crews. Thus the components of scheduling are 'Aircraft', 'Personnel' and 'Maintenance'.

2.2.3 Level 3 to 5

The components of Level 2 (Platform, Infrastructure, and Schedule) are further analysed as above, for the development of Level 3 to 5 components.

2.3 FMS Design & Development – Requirements Analysis

The **FMS** design & development requirements are derived from the operational support needs, operational environment needs and MRH and Health and Usage Monitoring (HUMS) technology needs. The operational support needs are for civil and military mission requirements. The military requirements comprise of naval and army missions off shipbased, air fields and forward air bases. The operational environmental needs are in natural and manmade environments, comprising of the type of terrains, weather, the operational time and the threat to the platform and personnel. The MRH and HUMS technology needs comprise of the technical requirements of the platform and its health monitoring systems from a support perspective.

2.3.1 Operational Support Needs

The analysis of operational support needs covers the present and future rotary-wing roles and missions of the operators. It includes support to provide air mobility in support of troops, equipment and casualties. In addition to

providing administrative support it also includes tactical support for special operations, communications, surveillance and limited armed support. The MRH is also to provide training to the crews on these roles. The key attributes derived from the MRH roles and missions is providing mobility to troops & equipment and medical & casualty transportation battlefields. The MRH provides tactical and logistic support to special operations groups, conducts reconnaissance & surveillance tasks and provides intelligence. The MRH is also a training platform for both air and ground crews. Thus high manoeuvrability and situational awareness is needed to enhance the survivability on such roles. A summarised mission analysis of the roles is presented in Tab.6, which systematically identifies the design and development requirements / attributes of the FMS.

The identified attributes (Tab.6) are the functional characteristics of the components of the system - Platform, Infrastructure and Schedule. The characteristics mav he attributable to either one or more components. The attribute 'Training' is of all three components, the platform is needed for the training, the Infrastructure is to provide the operating base and equipment and the personnel are to be scheduled for the training. The attributes are accordingly analysed vis-à-vis the components stipulate its functional to characteristics. The attributes of the components based on operational support needs is presented in Tab.1.

2.3.2 Operational Environmental Needs

The operational environment analysis investigates the environment in which the MRH platform is designed to operate and its impact on the technology. The environment plays an essential role in helicopter design, operations, support and safety. It affects mission accomplishment, maintenance, fatigue, crew load and costing. The MRH operational environment comprises of natural and manmade environments.

The platform operators deploy equipment on a regular basis to conduct disaster relief, peacekeeping and military operations. The system considers operations in various climates & terrains, Antarctic regions are also considered.

The natural environment covers the types of terrain, climatic conditions, time of operation and threat to operations.

• Terrain: The major section of Australia consists of deserts or semi-arid areas medium altitude mountains, rainforests and a large coastline. The overseas deployment terrain covers deserts. high mountains, tropical rainforest, and sea. The operational environment needs in such terrain are appropriate maintenance support in all terrains, visibility situational or

- awareness of own location, and manoeuvrability in restricted space. Training of crew will be needed for operation in these terrains.
- Climate: The ADF operates its rotarywing platforms in climates of Australia and overseas. The climate around the world covers temperatures ranging from very hot to severe cold. The humidity also varies based on the terrain of operation including the snow & sand conditions and rain. In the Australian region the coastal and desert operation places the high temperature humidity conditions. Thus. the operational environmental needs in such climatic conditions are the required maintenance support, visibility situational awareness in the extreme weather conditions and training of the crew to operate in all weather [14, 15].
- <u>Time</u>: The MRH operational environment covers day and night time operations. Hence, the operational environment need is round-the clock operations. The components will need to provide adequate visibility for situational awareness and the crew will need to be trained accordingly.

Operational Environment	Environment Analysis	Design & Development Requirements / Attributes
Terrain	Operation in Deserts / Mountains / Rain Forests / Sea	Maintenance Support Situational Awareness Manoeuvrability Training
Climate / Weather	Hot and severe Cold Snow & Sand & Rain Conditions Humid Conditions	Maintenance Support Situational Awareness Training
Time	Round-the Clock Operations	Situational Awareness Training
Threat (Natural / Manmade) Hills / Mountains / Trees Urban Built-Up Adversary		Situational Awareness Manoeuvrability Maintenance Support Armed Support / Survivability Training

Tab.2. MRH Operational Environment and Analysis to identify Requirements / Attributes

Components	Platform	Infrastructure	Schedule
Attributes -	Situational Awareness	Maintenance Support	Maintenance Support
	Manoeuvrability	Training	Training
	Armed Support / Survivability	-	-
	Training	-	-

Tab.3. Components and Attributes based on Operational Environmental Needs

Threat: The natural threats in the operational terrain include hills. mountains and trees. To avoid flight into these natural threats, visibility or situational awareness of own position and manoeuvrability is critical for survivability. Thus. the operational environment needs are situational manoeuvrability awareness, and survivability.

The manmade operational environment comprises of threat due to urban development and that from the adversary. This will need to be compensated by situational awareness of the threat, manoeuvrability and on-board weapons to counter the adversary. Additionally, the manmade environment will induce stress and accordingly will impose training needs. The environment needs are situational awareness, maintenance support, armed support or survivability, and training.

The analysis of the various environments in which the MRH will operate resulted in the identification of the **FMS** design development requirements or attributes of the FMS. A summarised environment analysis is presented in Tab.2 which systematically identifies the design development requirements / attributes of the FMS.

The identified attributes are the functional characteristics of the components of the system - Platform, Infrastructure and Schedule. As discussed in Sec.2.3.1, the characteristics may be attributable to either one or more components. The analysis of the attributes vis-àvis components is presented in Tab.3.

2.3.3 MRH & HUMS Technology Needs

The investigation of MRH & HUMS technology inputs to the design process of the FMS is to stipulate the design and development requirements. The technology has two versions – Tactical Transport Helicopter (TTH) and NATO Frigate Helicopter (NFH).

The technology provides enhanced operational flexibility & efficiency through common operational, training & logistic systems and the capability to rotate personnel, aircraft, spare parts and equipment between troop lift, special operations and maritime support roles and missions. Thus the maritime support and training requirements are similar to both technologies.

The MRH TTH version is to be operated from sealed, prepared and unprepared surfaces and the NFH version is to operate from ships to meet tactical transport requirements. Hence the manoeuvrability & survivability requirements are similar including maintenance support requirements on ships / unprepared areas. Additionally, electromagnetic compatibility is critical while operating from ships.

The design and development of the MRH helicopter includes the implementation of **HUMS** technology for condition-based maintenance. The two key components of HUMS for the MRH are the ground and aerial system. These systems are referred as follows: a) Ground System - Ground Management System (GMS); and Aerial System - Diagnostic System (DS). The GMS provides the required information to initiate / perform the appropriate maintenance activities. The DS is to provide the required diagnostic & prognostic functions for maintenance.

Technology	Technology Analysis	Design & Development Requirements
MRH (TTH & NFH)	Operational Flexibility by Commonalty in Logistic Support and Training Operation from unprepared Surfaces / Ships	Maintenance Support Training Manoeuvrability Survivability
	2337	Electromagnetic Compatibility
HUMS	Health Monitoring On-Board and initiate	Prognostic & Diagnostics
1101110	Maintenance Activity	ctivity Maintenance Planning

Tab.4. MRH & HUMS Technology Analysis to identify Requirements / Attributes

Components	Platform	Infrastructure	Schedule
	Survivability	Electromagnetic Compatibility	Maintenance Support
Attributes	Prognostics & Diagnostics	Training	Training
	Electromagnetic Compatibility	Maintenance Planning	-

Tab.5. Components and Attributes based on Technology Needs

The analysis of the MRH and HUMS technology further identifies the FMS design & development requirements. A summarised technology analysis is presented in Tab.4, that systematically identifies the requirements / attributes.

The identified attributes (Tab.4) are the functional characteristics of the components of the system Platform, Infrastructure and Schedule. As discussed in Sec.2.3.1, the characteristics may be attributable to either one or more components. The analysis of the attributes vis-à-vis components is presented in Tab.5.

2.3.4 Design & Development Requirements / Attributes

The analysis of the Operational Support Needs (OSN), Operational Environment Needs (OEN) and the MRH & HUMS Technology (MHT) identified the inputs to the design process of the FMS. These inputs provide the functional characteristics / attributes of the FMS. The functional characteristics / attributes of the

subsystems (Platform, Infrastructure and Schedule) are presented in Tab.7.

2.4 System Structure

The system structure is a representation of the components & attributes [11, 12] and the inputs and outputs in an 'Input-Process-Output' configuration. The analysis of the FMS from this perspective identified the components as 'Platform', 'Infrastructure' and 'Schedule' by the development of the system hierarchy (Sec. 2.2). The attributes of these components (design and development requirements) were derived by the analysis of the operational support needs, operational environment needs and MRH & HUMS technology needs (Sec. 2.3).

The holistic relationships for the design process between the components and attributes are the inter and intra – component & component, component & attribute, and attributes & attribute. The system structure at Level 1 of the system hierarchy is presented at Fig.3.

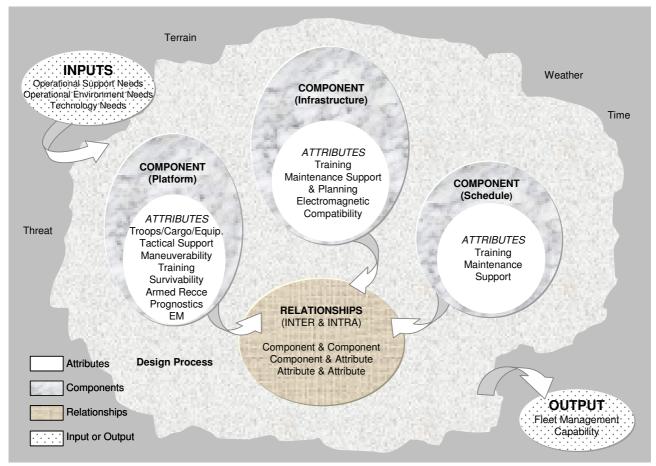


Fig. 3. FMS System Structure in an Input-Process-Output Configuration – Level 1

The Level 1 system structure is further analysed for the development of the Level 2 structure. At Level 2, the structures will need to be developed for the three subsystems (Platform, Infrastructure, and Schedule). The components of three subsystems are identified in Sec. 2.2.2 on the system hierarchy. The components are the following: a) Platform - Mechanical & Avionic Systems, Structure, Rotor System, Power Plant & Payload; b) Infrastructure - Operating Bases, Personnel & Equipment; and c) Schedule - Aircraft, Equipment & Personnel. The attributes of these components are analysed on similar lines as Sec. 2.2.2.

The inputs at Level 2 to the three systems (Platform, Infrastructure and Schedule) are analysed based on the attributes of these systems. The required inputs to the Platform remain as at Level 1, while that of the Infrastructure is governed by the support and environmental needs; and for schedule by an

additional input of the expected operational readiness benchmark. The output of the platform is mission capability, of Infrastructure is support capability, and that of the subsystem Schedule is fleet availability.

3 Results & Discussion

The FMS was considered in an Input-Process-Output configuration for a systems perspective on the inputs, design process and the outputs. Results cover the development of a system hierarchy to identify the subsystems / components of the FMS. Additionally, the system structure identified the attributes / functional characteristics / design & development requirements of the subsystems / components.

The three key inputs were the following: a) Operational Support Needs, b) Operational Environment Needs, and c) MRH & HUMS Technology Needs. The FMS comprised of three subsystems. The 'Platform' which

provided the mission capability, the 'Infrastructure' that provided the support for fleet management and the 'Schedule' for planning the fleet management. The analysis of the inputs stipulated the design & development requirements of the FMS. It covered from maintenance support to training and troops / equipment transportation to tactical support. These requirements were further analysed and designated to the subsystems for further consideration in the design & development of the FMS.

The FMS is customised for demonstration and application on the MRH platform. To provide versatility, the system hierarchy, methodology and simulation model developed on a modular basis. It supports the system application on other rotorcraft platforms. To achieve system versatility, the component 'platform' and its sub-components in the hierarchy are interchangeable to suit other helicopter platforms and are based on the ATA specification 100 [13]. The components 'Infrastructure' and 'Schedule' are modified accordingly in the MRH specific sections.

4 Concluding Remarks

The main characteristics of the research conducted are the application of a systems approach to address the complexity of rotarywing operations & support. The approach assists in structuring the issues & challenges faced in designing a technology support management methodology in the operators covering the various aspects of a helicopter life-cycle.

It covered investigations on the present and future helicopter fleets and the fleet needs of the operators. The research addresses the civil & military fleet management practices of operators worldwide to develop FMS system & software design requirements. The next phase of research will develop the FMS methodology and establish a customised simulation model for application on the MRH platform.

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Role	Mission Analysis	Design & Development Requirement / Attributes	
Airmobile Mission (AMO) – Land	Air Insertion, Air Re-Supply,	Troops / Equipment	
7 III III OO II 1711331ON (7 II 17 O) LUNG	and Air Extraction - Land	Transportation	
AMO – Amphibious	Air Insertion, Air Re-Supply,	Troops / Equipment	
	and Air Extraction - Coastal Areas	Transportation	
Artillery AMO / External Load Mission	Air Insertion, Air Re-Supply,	Troops / Equipment	
MISSIOII	and Air Extraction - Artillery / Sling Loads	Transportation	
Air Movement	Provide and enhance Mobility of Troops and Cargo	Troops & Cargo Transportation	
Ferry	Deliver / Transfer Aircraft between two Locations	Aircraft transfer	
Aeromedical Evacuation	Tactical and Strategic medical Transportation	Med / Cas Evac	
Command, Control, Communication, Electronic Warfare (EW)	Provide observational Information, manage Battlefield, provide Command and Control to all Assets, use of Electromagnetic Energy to confuse/disable Enemy Defensive Systems	Intelligence & EW	
Support Operations	Enhance military Survivability	Survivability	
Training 1- Tactical	Practice Battlefield Tactics	Training	
Training 2 - Circuits	Practice Air Base Patterns	Training	
Training 3 - IFR	Practice under Instrument Flight Rules	Training	
Training 4 - Deck Landing Practice	Practice Landings on Ship Decks	Training	
Special Operations (SO) Support	Provide Mobility and Support to SO Group	Tactical Support	
Combat Search and Rescue	Aid in Search and Supplement Rescue in Battlefield	Med / Cas Evac	
Logistics Support (Maritime)	Provide Naval Logistic Supplies and Equipment	Transport Cargo / Equipment	
Anti-Surface Warfare	Detection and neutralisation of enemy Surface Targets	Armed Reconnaissance & Surveillance	
Helicopter Visit, Board, Search and Seizure	Support maritime Boarding Actions and Tactics	Tactical Support	
Aerial Mine Search and Disposal	Detection and Neutralisation of Mines	Reconnaissance & Surveillance	
Maintenance Test Flight / Ground Run	Prove Serviceability before Return to Service	Maintenance Support	

Tab.6. MRH Roles and Missions Analysis to identify Requirements / Attributes

lule	SN MHT	nance Maintenance bort Support	ning Training	1	1	1	
Schedule	SN OEN	ning Maintenance Support	nance Training	1	1		
	NSO	oblic Training tii-	Maintenance Support	nnce .	1	ı	
ıre	MHT	Electro- magnetic Compati- bility	Training	Maintenance Planning	1	1	
Infrastructure	OEN	Maintenance Support	Training	,	1	ı	
Platform	NSO	Training	Maintenance Support	ı	1	ı	
	MHT	Survivability	Prognostics & Diagnostics	Electro- magnetic Compati- bility	ı	ı	
	OEN	Situational Awareness	Manoeuvra- bility	Maintenance Support	Armed Support / Survivability	Training	
	NSO	Troops / Cargo / Equipment Transport	Tactical Support	Survivability	Armed Recce & Surveillance	Med / Cas Evac	
Component	FMS Design Process Inputs (Requirements Analysis)	FMS Design & Development Requirements (Attributes of FMS Components)					

Tab.7. Summary of FMS Components and Attributes

OSN: Operational Support Needs OEN: Operational Environment Needs Legend:

MHT: MRH & HUMS Technology

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