

Research on FSI dynamic characteristics of parafoil trailing edge deflection

GAO Xinglong¹, ZHANG Qingbin², LI Zhihui³, CHEN Qin¹ & WANG Wenkai⁴

¹State Aerodynamic Key Laboratory, China Aerodynamic R&D Center, Mianyang, China, 621000

²College of Aerospace Science and Technology, National Defense Technology University, Changsha, China, 430100

³Beijing Pioneering Innovation Center of China Aerodynamics Research and Development Center, Beijing, China, 100191

⁴Technology Center, AVIC Aerospace Life-Support Industries. Ltd, Xiangfan, China, 441001

Abstract

The parafoil is manipulated by pulling the trailing edge to realize maneuvering, turning, and landing etc., which involves the coupling process between the flexible fabric structure and aerodynamics. Based on the transient nonlinear dynamics' method, the FSI dynamic behaviors of trailing edge deflection is numerically simulated and analyzed. The Structured-ALE (SALE) models algorithm as well as the penalty method are both utilized to modeling the coupling fields and interface, by which the computing efficiency is highly improved. The stress distribution and structure strength of canopy is visualized and analyzed, the surrounding flow field is also visualized in 3D, the evolution mechanisms such as flow separation are studied. At last, the influence of deflection angle as well as the turning position on FSI dynamic characteristics are comparatively analyzed. The results validated the efficiency of our method and could be a good support for the design and application of large parafoil.

Keywords: Parafoil, Fluid structure interaction, Trailing edge deflection; ALE method; Flow separation

1. Introduction

Parafoil is originating from parachute-airfoil, which is a controllable and flexible aerodynamic structure with several cross sections divided by the airfoil type ribs distributed between upper and lower ceiling surfaces. The upper surface is mainly bearing the aerodynamic loads, while the lower surface is mainly bearing the opening impacts, thus the local broken of lower surface wouldn't cause the whole damage of parafoil's aerodynamic characteristics[1]. The fabric's permeability of parafoil is extremely low to make the ram air from leading edge of airfoil during the flight, and the internal pressure in cross sections can keep the airfoil shape of parafoil in flight phase. Comparing with the traditional parachute, the biggest advantage of parafoil is manipulating performance. The manipulation of parafoil is performed by controlling the rigging lines to deflect the trailing edge, the aerodynamic configuration of parafoil will change during the maneuvering and flaring phases. The dynamic problems relating to the manipulation and deflection is overly complex[2]. The world have never stopped the research on the parafoil since it born in 1960's, and gradually formed many advance parafoil precision airdrop systems, which have been successfully applied in both the military and civilian fields. The famous case like Joint Precision Airdrop System (JPADS) of United States, JPADS is a precision guided airdrop system that provides rapid, precise, high-altitude delivery capabilities that do not rely on ground transportation[3]. The system is being developed in two weight classes: 2000 pounds and 10000 pounds. X-38 parafoil is another influential recovery system modified from the U.S. Army Guided Precision Air Delivery System (GPADS), which can achieve a repeatable, low dynamics on heading opening of the full-scale ram-air parafoil[4]. The X-38 parafoil is the biggest parafoil project worldwide until now with 700m² deployment area and 33 cells. And there are other distinguished parafoil systems like Canadian Snow Goose surveillance system and Sherpa precision airdrop system, the European SLG-Sys autonomous gliding airdrop system etc. The working process of parafoil is a typical fluid-structure interaction (FSI) problem involved with

interaction between canopy structure and surrounding aerodynamic pressure. The solving of FSI problems have always been a concerned problem in parachute research field.

To build a reasonable FSI dynamic model can effectively predict the deforming behavior of canopy structure as well as the response of aerodynamic configuration, especially can simulate the damage phenomenon beforehand, and could be a good support for the optimal design of flight system. There is still a lack of extensive attention on the FSI dynamic mechanism specifically focus on the parachute system. Tang etc. simulated the structural behaviors during trailing edge deflection of parafoil based on the ICFD flow solver and mechanical solver[5]. Tezduyar group performed the FSI simulation on ram air parafoil system based on DSD/SST FEA method[6]. Fogell etc. carried out the FSI simulation on the canopy shape during parafoil's steady flight state based on loose coupling method with CFD and CSD techniques[7]. Altmann analyzed the FSI problems of parafoil by potential flow theory as well as the simplified FEA method[8]. Cao etc. analyze the FSI problem of parafoil inflation by Dichlet/Neumann iteration method[9]. Teng etc. realized the FSI simulation for the steady aerodynamic configuration of parafoil based on LS-DYNA software[10]. He etc. simulated the billowing phenomenon of parafoil's cell by cable-membrane FEA model and CFD technique[11].

For the large scale parafoil system, the dynamic characteristics of interconnected cells are crucial for the whole canopy and parafoil. As the basic element of canopy structure, this paper firstly focuses on the FSI dynamics of single cell during the trailing edge deflection process, to obtain the aerodynamic loads on surface as well as the structural response of fabric.

2. Fluid structure interaction modeling

2.1 Structural dynamics

The parafoil structure is mainly composed with the fabric, upon which only the main stress exists under loading. The governing equations of fabric structure can be stated as[12]

$$\rho_s \frac{\partial \mathbf{u}}{\partial t} = \boldsymbol{\sigma}_s(\mathbf{u}) + \rho_s \cdot \mathbf{f}_s \quad \text{on } \Omega^s \quad (1)$$

Where ρ_s is the material density, \mathbf{u} is the velocity vector of structure point, $\boldsymbol{\sigma}_s$ is the Coriolis stress tensor, \mathbf{f}_s is the outer force acting on the structure.

Considering the nonlinear characteristics of fabric structure dynamics, the membrane element is used to simulate the fabric, of which the constitutive equation is

$$\begin{aligned} \varepsilon_1 &= \frac{1}{E_1}(\sigma_1 - \nu_1 \sigma_2) \\ \varepsilon_2 &= \frac{1}{E_2}(\sigma_2 - \nu_2 \sigma_1) \end{aligned} \quad (2)$$

Where σ_1 , ν_1 , E_1 are serpeartelly warp stress, poisson's ratio and elastic module, accordingly, σ_2 , ν_2 , E_2 are serpeartelly weft stress, poisson's ratio and elastic module.

2.2 Fluid dynamics

he flow around the parafoil in this paper is low speed and incompressible, the Euler governing equation of fluid is used as follow[13]

$$\rho_f \left(\frac{\partial \mathbf{u}_f}{\partial t} + \mathbf{u}_f \cdot \nabla \mathbf{u}_f + \mathbf{f}_f \right) - \nabla \cdot \boldsymbol{\sigma}_f = 0 \quad \text{on } \Omega^f \quad (3)$$

$$\nabla \cdot \mathbf{u}_f = 0 \quad \text{on } \Omega^f \quad (4)$$

Where ρ_f and \mathbf{u}_f are density and velocity vectors, \mathbf{f}_f and $\boldsymbol{\sigma}_f$ are outer force and stress tensors.

By introducing the Arbitrary Lagangrian and Eulerian formulation, the finite element mesh can move freely, and the fluid governing equation can be rewritten in ALE formulation as

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} - \mathbf{w}) \cdot \nabla \mathbf{v} - \frac{1}{\rho_f} \boldsymbol{\sigma} = \mathbf{g} \quad (5)$$

Where the fluid particle velocity is $\mathbf{u}_f = \mathbf{v} - \mathbf{w}$, \mathbf{v} and \mathbf{w} are separately the partial and mesh point velocity under reference configuration. The Dirichlet and Neuman's boundary conditions are

$$\begin{aligned} \mathbf{v} &= \mathbf{g}(t) & \text{on } \partial\Omega_1^f \\ \mathbf{n} \cdot \boldsymbol{\sigma} &= \mathbf{h}(t) & \text{on } \partial\Omega_2^f \end{aligned} \quad (6)$$

Where Ω_1^f represents the velocity boundary of fluid field, and Ω_2^f represents the coupling boundary between fluid and structure.

2.3 Penalty method

Another key technique for the FSI problems is the information transfer on coupling interface. The energy conservation should be maintained during the transmission. Normally, it is difficult to realize the total matching between fluid and structure mesh in FEA, while it is possible to perform such technique by ALE penalty method in this paper.

In explicit dynamics integration method, the penetration depth at next time step should be [14]

$$\mathbf{d}^{n+1} = \mathbf{d}^n + \mathbf{v}_{rel}^{n+1/2} \cdot \Delta t \quad (7)$$

Where Δt is the time step, and \mathbf{v}_{rel} is the relative velocity between the master and slave points. The master point velocity can be seen as the fluid element point velocity during the motion in ALE formulation, then

$$\mathbf{v}_{rel}^{n+1/2} = \mathbf{v}_s^{n+1/2} - \mathbf{v}_f^{n+1/2} \quad (8)$$

The penetration occurs only when $\mathbf{n} \cdot \mathbf{d}^n < 0$, and the coupling force is

$$\mathbf{f}_c^n = k \cdot \mathbf{d}^n \quad (9)$$

Where k is the stiffness coefficient, and the equilibrant can be loaded as

$$\mathbf{f}_s^n = -\mathbf{f}_c^n \quad (10)$$

Then transform the fluid force into the i point by the shape function N_i

$$\mathbf{f}_f^{i,n} = N_i \cdot \mathbf{f}_c^n \quad (11)$$

For solid element, $\sum_{i=1}^8 \mathbf{f}_f^{i,n} = \mathbf{f}_c^n$, which satisfy the acting force interaction principle on coupling interface.

3. Numerical model

The numerical model for parafoil's cell FSI simulation is illustrated in Fig.1, of which the cell is inflated in billowing state, and meshed by the FEA elements. And the meshes of fluid field are built and formed by the simplified ALE (SALE) technique during the simulation process. The SALE method only need the spacing and bunching laws on the edges of fluid field beforehand, and the structure mesh would automatically generated during the integration steps, which greatly decrease the solution time and improve the simulation efficiency for such complex explicit dynamics integration problems.

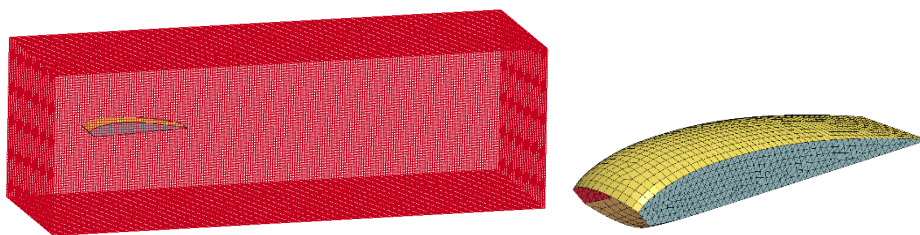


Figure 1 –FSI model of cell in billowing state.

4. Simulation results

4.1 Fluid field results

The simulation results including the velocity contours of fluid field is illustrated in Fig.2, from which you can see the evolution details of flow surrounding the structure during the trailing edge deflection process. The vortices born from the upper surface and gradually transits to the trailing edge, most of them are broken during the evolution process. The flow separation phenomenon can also be seen from the figures, which is caused by the obvious low speed region on the upper of trailing edge when the deflection angle increases.

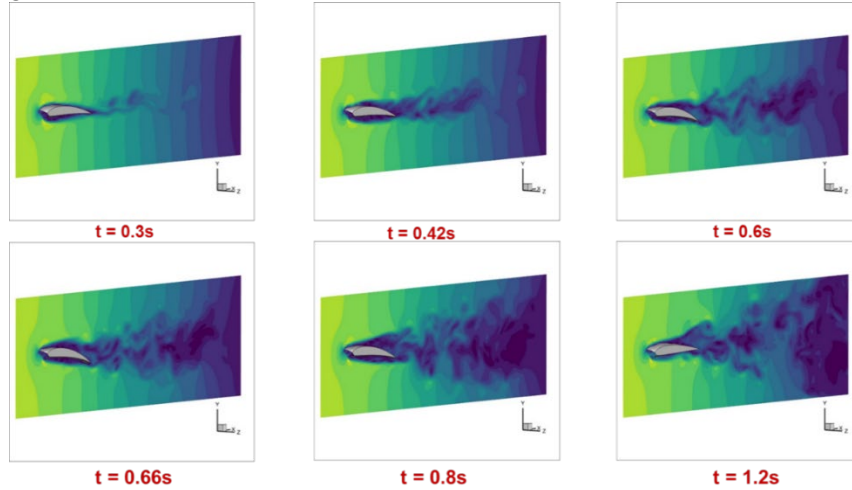


Figure 1 –Velocity contours of fluid field during trailing edge deflection process at time 0~1.2s

4.2 Structural field results

The structure field of cell's canopy under the aerodynamic pressures can also be obtained during the FSI simulation. As the Fig. 3 and Fig. 4 shows, the stress and pressure distributions on the canopy are nonuniform significantly during the deflection process. And the high stress region mostly concentrate upon the central forepart of upper surface, which would easily cause the stress concentration phenomenon on this area.

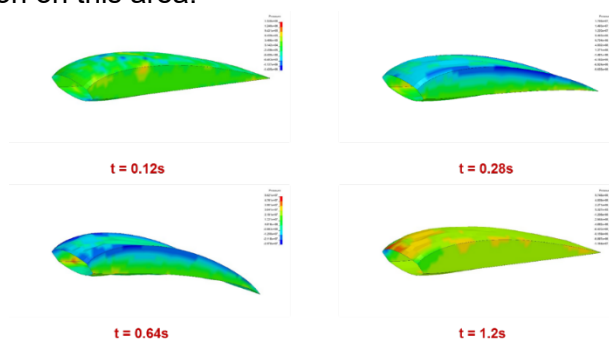


Figure 2–Structural stress distribution contours on cell's canopy during trailing edge deflection process at time 0~1.2s

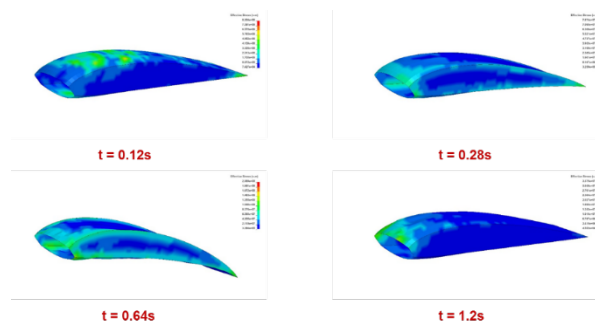


Figure 3–Pressure distribution contours on cell's canopy during trailing edge deflection process at time 0~1.2s

5. Conclusion

The FSI dynamics problem for inflated parafoil cell during trailing edge deflection process is analyzed in this paper. The simulation results show: the SALE technique as well as the penalty method are effective for the FSI simulation of such large translation combined with the structure deformation behaviors, both the fluid and structure evolution details could be visualized to predict the dynamic behaviors of parafoil trailing edge deflection. All in all, the achievements in this paper could be a significant tool and support for the design of large parafoil precision airdrop system.

6. Contact Author Email Address

Gao Xinglong: 18674853560@163.com

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