TESTING OF THE AGARD B/C, ONERA AND SDM CALIBRATION MODELS IN THE T-38 1.5m x 1.5m TRISONIC WIND TUNNEL

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Abstract

During commissioning of the T-38 Trisonic wind tunnel of VTI, AGARD B/C, ONERA M4 and SDM models were tested. AGARD models were tested in the subsonic, transonic and supersonic speed regimes. The test results are confined to the results from similar facilities as Boeing 4 T, INCREST 1.2 m and NAE 5 ft. wind tunnels at Mach numbers from 0.7 to 2.0. Description of measuring equipment and analysis of results are presented. ONERA M4 model was tested in transonic speed regime to check out the transonic test section force, moment measurement and flowstream quality. Obtained test results on ONERA M4 model are in satisfied agreement with published data obtained on ONERA M5 model in other reference wind tunnels. The equipment for derivative stability measurement was verified investigating SDM (Standard Dynamic Model) in the subsonic test section at $M = 0.6$. Brief description of the model and equipment are presented. Main static and dynamic derivatives are plotted as a function of angle of attack and compared with the results obtained in NAE and AEDC wind tunnels.

I Nomenclature

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
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<tbody>
<tr>
<td>ALFA$\alpha$</td>
<td>incidence</td>
</tr>
<tr>
<td>$\beta$</td>
<td>side slip angle</td>
</tr>
<tr>
<td>b</td>
<td>wing span</td>
</tr>
<tr>
<td>$C_{pb}$</td>
<td>base pressure coef. = (Pbase- Pst)/q</td>
</tr>
<tr>
<td>$C_D$</td>
<td>drag coefficient = drag/qs</td>
</tr>
<tr>
<td>$C_L$</td>
<td>lift coefficient = lift/qs</td>
</tr>
<tr>
<td>$C_n$</td>
<td>normal force coefficient</td>
</tr>
<tr>
<td>$C_m$</td>
<td>pitching moment coefficient</td>
</tr>
<tr>
<td>$C_{MALFA}$</td>
<td>$C_{ma}$</td>
</tr>
<tr>
<td>$C_{I\beta}$</td>
<td>$\beta C_l(\beta) \sin \alpha$, $i = l, n$</td>
</tr>
<tr>
<td>$C_{NBALF}$</td>
<td>$\beta C_n(\beta) \cos \alpha$</td>
</tr>
<tr>
<td>$CMQ^*$</td>
<td>dynamic composite fixed axis pitch derivative</td>
</tr>
<tr>
<td>$CNR^*$</td>
<td>dynamic composite fixed axis yaw derivative</td>
</tr>
</tbody>
</table>

$CIP^*$ dynamic composite fixed axis roll derivative
$D$ model diametar
$M$ Mach number
$MRe$ Mega Reynolds number based on mean aerodynamic chord

subscripts
n nominal condition

II Introduction

During the commissioning of the Vazduhoplovnotehnicki Institut (VTI) trisonic blowdown wind tunnel T-38 a series of tests were performed to check the test section flow quality and used measuring equipment and to compare the results with the same obtained in other wind tunnels. T-38 wind tunnel has been operational since 1986. Subsonic and supersonic test sections are with solid walls while transonic test section has porous walls, with variable porosity of up to 8%. Dimensions of the 3D working section are 1.5 m x 1.5 m. 2D test section size is 0.38 m x 1.5 m. Mach number range is 0.2 to 4. with stagnation pressure 1.8 to 14 bar. Run time duration depends on both Mach number and stagnation pressure, varying from 6 sec. to 60 sec. More information is given in (1).

AGARD B and C and ONERA M4 calibration models were used for force and moments comparison tests and SDM model for dynamic derivatives testing. AGARD models were taken on loan from DSMA/Boeing company. ONERA M4 model was manufactured because the existing ONERA M3/M5 models are not quite representative both in scale and load capacity for the T-38 1.5m transonic test section. SDM model was fabricated with the identical geometry as the corresponding AEDC model. Brief description of models and used test technique are presented.

III Testing of the AGARD models B/C

Model description

The AGARD B and C wind tunnel calibration models used in the test programme were supplied by DSMA/Boeing company. In Fig.1 are shown models...
with the pertinent dimensions given in terms of the body diametar D. Model B consists of a wing and body combination, where the wing is an equilateral triangle with a span of four times the body diametar. Model C is identical to Model B, except that the body is extended aft by 1.5 body diameters and vertical and horizontal tail surfaces are added as shown in the Figure. Both models have been used in previous wind tunnel calibrations and therefore there is an extensive data base already existing with which to compare the results obtained from the present programme.

Measuring equipment and test programme

Aerodynamic forces and moments were measured with a six-component 2-inch diametar internal lineary calibrated Able MKXVIII balance. There was found a max. error of 0.4% relative to the applied max. load in calibration, including interactions and hysteresis.

The model was mounted on a sting specially designed in accordance with AGARD recommendation for such tests. The models were used to provide force and moment data and only one KULITE 7 bars absolute pressure sensor was used for base pressure measurements. Stagnation and static pressure were measured with 17 bar and 7 bar Mensor abs. transducers in the settling chamber and test section side wall, respectively.

The outputs from the balance, base pressure transducer and other measuring sensors (model positions and primary measuring systems) were transmitted to TELEDYNE 64 channel, 16 bit A/D conversion data acquisition system. Max. sampling rate is 125,000 samples/sec and overall precision is less than 0.1% F.S. In the present test approx. 200 samples per channel were taken at 500 samples/sec. sampling rate. Data acquisition was controlled by PDP 11/34 computer. Raw data were transferred to a VAX 11/780 computer, where data reduction was performed. An application software package developed by VTU was used in this test, by which most of the data reduction process was automated.

The model forces were converted to the wind axes system. All measurements were made with natural transition.

The initial test programme called for approx. 40 wind tunnel runs. Most of those were in the transonic test section. Tests were conducted at Mach Number between 0.5 and 2.0 at moderate blowing pressure. Reynolds number based on mean aerodynamic chord was very high, eg. $M = 1.0$ MRe=8.

AGARD Test Results

This paper will present the results of only a few typical runs. In order to compare the results with those in other facilities, three similar wind tunnels were selected: NAE 5ft. (2) BOEING 4T (3) and INCREST 1.2m x 1.2m. (4)

Fig.2 presents a comparison of AGARD B data for selected subsonic Mach numbers in the range from 0.76 to 0.80 in Boeing, INCREST and NAE wind tunnels. The data obtained in the present test (VTI) are in good agreement with the other data, except for the pitching moment, $C_m$ obtained in Boeing and INCREST. $C_m$ in the present and NAE tests is significantly larger than both Boeing and INCREST values, and has the opposite sign. In order to confirm which data are correct, a review of measurements on AGARD calibration models was examined. It was found that the T-38 and NAE values of $C_m$ agreed well with standard results of (5) and two data points from this reference are plotted in the Figure. It is possible that in the Boeing and INCREST tests, $C_m$ was computed in a different manner. The Mach number variation is plotted in Fig.2 for the present data. Variations are very small during the run.

A comparison of AGARD-C data obtained in the VTI T-38 transonic test section is shown in Fig.3. All four sets of $C_L$ data agree very well and have the same slope. Values of $C_D$ from the data sets agree well over the range of $C_L$ for which comparable data are available. The VTI and NAE values of $C_D$ lie between the INCREST and Boeing values. $C_m$ data from the three data sets, however, show no similarity whatsoever. $C_m$ in the T-38 and NAE data is always positive, even for negative incidence, whereas for the INCREST and Boeing data, it tends to be negative for positive incidence and vice versa. Points for $C_m$ corresponding to $C_L=0, 0.2$ and 0.4 obtained from (6) are plotted in the Figure. They very well agree with the results obtained in the present test. Note, however, that (6) states that AGARD-C pitching moment results from different tests have a lot of scatter. The results in Fig.3 confirm that observation.

Fig.4 compares the VTI data obtained in the supersonic test section at $M=2.0$ with data from the other facilities. The agreement between the four data sets is very good, including the agreement of the $C_m$ data. VTI values of $C_m$ agree with the INCREST and Boeing data, not only in magnitude, but also in sign.

IV Testing of the ONERA M4 model

Model description

ONERA designed a family of hypothetical models which represents typical transport aircraft configuration for research aerodynamic phenomenon in transonic regime enclosed by tunnel walls, such as: blockage and Reynolds number effect and effect of downwash. For that reason ONERA model, the geometry illustrated in Fig.5 is designed and constructed in scale M1, M2, M3 and M5 covering wing span of 0.3m to 1.0m approx. for testing in various wind tunnels world-wide.

Since the ONERA M5 model would produce a signif-
significant interference effect in the T-38 test section while ONERA M3 model aerodynamic loads are not representative for designed model load capacity, it was decided to manufacture ONERA M4 model (D=0.102m, b=0.8m). Global measured dimension accuracy is better than 0.03mm. The inside space of model is adopted to accept ABLE strain gauge balance of 2 inch diam., MK-XVIII installed on specially designed ONERA sting the geometry of which is presented in Fig.5.

Measuring equipment and test programme

The test programme, concerning Mach number, incidence and Reynolds number is based on the programme carried out in other wind tunnels with ONERA M5 model. Testing is performed at nominal Mach numbers of: 0.7, 0.78, 0.82, 0.86, 0.88, 0.92 and 0.94 at moderate blowing pressures. The pitch angle range was -6° to +6°. Model positioning was performed in a step by step mode with accuracy better than +/-0.05°. The data acquisition was performed by Teledyne front ends. Each transducer was supported by a separate channel from which were taken 200 samples per angle at the rate of 500 samples/sec/channel. Electrical signals passed through 10 Hz low-pass Butterworth filters. The force and moment measurements were done with linearly recalibrated ABLE 2.0 inch MKXVIII balance which had been used in AGARD tests mentioned above. The base pressure was measured by the DRUCK PDCR-42 differential transducer, 0.35 bars. The ROSEMOUNT absolute transducer was used for measurement of atmospheric pressure. Stagnation and static pressures were measured with the same transducers as mentioned in III.

ONERA Test Results

Among other requirements, the chosen scale of the ONERA M4 model was selected so, that the frontal area of the model does not exceed 1% of the wind tunnel cross-section, because the test results are not corrected due to blockage effect. On the other hand, the experiment was not able to reach condition of aerodynamic similarity (the same or similar M and Re) with those in North-American wind tunnels. The cause is safety loading factor 2 for ONERA M4 model which limited the stagnation pressure bellow 4 bars in testing.

The results are corrected due to base drag as well as model-sting deflection. Here are presented comparative tests results at nominal Mach number M=0.7 and M=0.94 obtained with the ONERA M4 model (VTI-T38) and with the ONERA M5 model (NAE,AEDC,NASA).

The two experimental data sets at Mach number M=0.709, MRe=4.29 and MRe=5.9, are presented in Fig.6 and Fig.7 respectively, to show typical Cm dependence on Reynolds number at higher incidence. Fig.6 presents the coefficients C D, C L and C m versus α in comparison with results published by AEDC (6) and NAE (7). Neither the magnitude nor the sign of C D coefficient, obtained in NAE could be comparable with the same, obtained in other wind tunnels including VTI-T38 results. (6). Fig.8 shows curves of the C D, C L and C m coefficients versus α at Mach number M=0.942 and MRe=4.34, (6) compared to the corresponding AEDC,NASA (6) and NAE (7) results. The results are in good agreement, except for C D coefficients obtained in NAE.

V Standard Dynamic Model Experiments

Model

Dimensions of the VTI Standard Dynamic Model (SDM) are presented in Fig. 9. The model was fabricated in VTI workshop from an aluminium alloy. The geometry of the model is indentical to the corresponding AEDC model(9). All presented results are referred to the 35 % mean aerodynamic chord point.

The model mass is 12.4 kg excluding balance. Dynamic wind-off measurements on the apparatuses yielded the following torsional moments of inertia: in pitch 0.328 kgm²; in yaw 0.338 kgm² and in roll 0.042 kgm²

Measuring System

According to Orlik-Ruckemann’s classification(10), the VTI apparatuses are sting supported mechanisms for inexorable small-amplitude angular oscillation of wind tunnel models.

Fig.10 shows the pitch/yaw apparatus(11). The suspension system consists of a pair of cross flexures that provide the necessary compliance in pitch or yaw, depending on the model orientation relative to the apparatus. The primary motion is imparted by the hydraulic driving mechanism in which the piston moves applying the driving force on the actuator arm. The forward end of the actuator arm is firmly attached to the moving end of the cross flexures. The cross flexures and hydraulic cylinder are manufactured as integral parts of the sting. In order to obtain the desired primary oscillation, the hydraulic actuator is driven by a hydraulic servo valve located at the sting base which is, in turn, driven by a signal from the control system. Provision is made to augment the suspension stiffness by adding a pair of adequate auxiliary leaf springs.

Fig.11 shows the roll apparatus(11). The suspension system consists of two rings joined by axially oriented beams equally spaced around the periphery of the rings. There are two suspension systems for low and high loads. The front end of the drive shaft is firmly fixed to the forward end of the suspension flexure. The oscillatory rolling motion is imparted by the hydraulic driving mechanism located at the rear end of the sting.

Apparatuses are mounted on the wind tunnel model
support system.

The total force and moment acting on the model are measured with a five component balance, with no axial measuring capability. The balance is made in a single piece and very stiff to keep any natural frequencies well above the oscillation frequencies. Because of its stiff design it is equipped with semiconductor strain gages. The strain gages are temperature compensated with the same precision as conventional wind tunnel balances.

The primary motion is sensed by strain gages located at the cross flexure system, in case of the pitch/yaw apparatus, or at the flexural support in case of the roll apparatus. Drive torques are sensed by strain gages located on the actuator arm or on the drive shaft. For measurement of the sting oscillation, the stings are fitted with strain gages that form a 3-component balance.

Table 1 lists the performance specifications of relevant apparatuses.

The standard data acquisition and control equipment of the wind tunnel are used for derivative measurement. The stability derivative control unit is a part of WTCS (Wind Tunnel Control System) and provides an automatic operating mode.

A typical wind tunnel run includes the following three stages:

- an amplifier calibration run, when known AC signals from the signal generator are fed to the data acquisition system;

- tare run, when the model is oscillated but the tunnel is not running;

- wind-on run, when the model is oscillated at the same frequency as during the tare run but with the wind tunnel running.

During the above measurements, all the sensor signals are amplified, filtered and then digitized by a 16-bit A/D converter. The sampling record of data covers, approximately, 20 - 70 cycles of the primary oscillation.

The data from test runs are processed by DEC computer VAX 11/780 by appropriate software package developed by VTI.

SDM Test Results

The test was conducted in the 1.5 x 1.5 m subsonic test section. The nominal Mach number was \( M_{\infty} = 0.6 \) and the Reynolds number \( MR_e = 4.3 \) based on the mean aerodynamic chord of the model. The stagnation pressure was 1.8 bar and the stagnation temperature was close to ambient temperatures. The symmetrical condition (\( \beta = 0^\circ \)) was tested for \(-2.5^\circ \leq \alpha \leq 21^\circ\).

The amplitude of primary motion was \( 1^\circ \) and excitation frequency of 5 Hz. Reduced frequency in pitch was \( \omega_r = 0.016 \) and in yaw and roll \( \omega_r = 0.041 \).

Fig. 12 shows curves of the longitudinal coefficients \( C_x \) and \( C_m \) compared to corresponding AEDC(9) and NAE(12) results. Discrepancy between measured coefficients \( C_m \) in VTI and NAE is probably attributable to wall and strut-interference effects in the solid-wall tunnel used for NAE tests(13).

The test results of the direct dynamic and static stability derivatives in pitch, yaw and roll are presented in Figures 13 to 15, as a function of \( \alpha \), in comparison with results published by AEDC(9) and NAE(12)(14). Nonlinear trends in the derivatives as a function of angle of attack are repeated with small discrepancies. Dynamic and static cross derivatives are presented in Fig. 16. The discrepancies between these two sets of data are the same as those obtained by DFVLR(15).

VI Conclusion

Experiments carried out using a AGARD B/C, ONERA M4 and SDM models in the VTI 1.5m blowdown wind tunnel have shown a good agreement with results from other wind tunnels. It can be stated that the present AGARD tests data agree quite well with Boeing, INCREST and NAE data, except for the pitching moment data. However, the VTI data show better agreement with NAE and the published results than the \( C_m \) results from two other data sets. These comparisons thus confirm the integrity of the VTI/T-38 and NAE AGARD data sets.

Small differences in flowstream conditions and geometrical similarity of ONERA M4 and ONERA M5 models should be the source of scattering in the compared results, because it could not be adequately aerodynamically quantified. Obtained \( C_D \) test results at VTI-T38 are not comparable with the same from NAE.

Presented test results of the SDM model verified the functionality, quality and precision of the new designed apparatuses for the derivative stability measurements in the T-38 wind tunnel. High load capacity of the apparatuses permit measurements of the derivative stability, at very high Re number in the subsonic, transonic and supersonic speed regimes.

References

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9 Uselton, B.L. "A Description of the Standard Dynamic Model (SDM)", 56th Supersonic Tunnel Association Meeting, October 1981


14 Beyers, M.E. and Moulton, B.E. "Stability Derivatives Due to Oscillation in Roll for the Standard Dynamic Model at Mach 0.6", NRC-LTR-UA-64, Ottawa, Jan 1983.


Table 1. - Performance of the Apparatuses

<table>
<thead>
<tr>
<th>Apparatus</th>
<th>Pitch/Yaw</th>
<th>Roll</th>
</tr>
</thead>
<tbody>
<tr>
<td>Amplitude</td>
<td>0.25 ÷ 1.50</td>
<td>0.25 ÷ 1.50</td>
</tr>
<tr>
<td>Frequency</td>
<td>0.2 ÷ 15Hz</td>
<td>0.2 ÷ 15Hz</td>
</tr>
<tr>
<td>Sting Dia.</td>
<td>elliptic 50 × 72</td>
<td>76mm</td>
</tr>
<tr>
<td>Hydr. pressure</td>
<td>200 bar</td>
<td>200 bar</td>
</tr>
<tr>
<td>Max. normal force</td>
<td>1000 daN</td>
<td></td>
</tr>
<tr>
<td>Max. incidence</td>
<td>21°</td>
<td></td>
</tr>
<tr>
<td>Mach number</td>
<td>M ≤ 2</td>
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</table>

Fig.1: Geometrical Arrangement of AGARD Models B and C
Fig. 2: Comparison of AGARD B Data for Subsonic Mach Numbers

Fig. 3: Comparison of AGARD C Data for Transonic Mach Numbers

Fig. 4: Comparison of AGARD B Data for Supersonic Mach Numbers

Fig. 5: Geometrical Arrangement of ONERA Model-Sting Configuration
Fig. 6: ONERA Data Comparison at $M_n = 0.7$

Fig. 7: ONERA Effect of Reynolds Number at $M_n = 0.7$

Fig. 8: ONERA Data Comparison at $M_n = 0.94$

Fig. 9: Geometrical Arrangement of SDM Model
Fig. 10: Forced Oscillation Pitch/Yaw Apparatus

1. Balance  
2. Cross flexure pivot  
3. Changeable leaf spring  
4. Piston  
5. Inductive Displacement Transducer  
6. Sting adapter  
7. Sting  
8. Moog Servovalve

Fig. 11: Forced Oscillation Roll Apparatus

m = 0.6

Fig. 12: Longitudinal Coefficients

\[ \text{C}_\text{y} \text{ vs. } \alpha \]

\[ \text{C}_\text{m} \text{ vs. } \alpha \]
Fig. 13: Pitch-Oscillation Coefficients

Fig. 14: Yaw-Oscillation Coefficients

Fig. 15: Roll-Oscillation Coefficients

Fig. 16: Cross Derivatives