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PROPAGATION OF THE SONIC BOOM IN THE
REAL ATMOSPHERE
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## Abstract

By virtue of linear theory of a sonic boom, the pattern of shock and rarefaction waves occurring in the supersonic flow past an aircraft,may be treated as a wavefront.If intensity of a sonic boom is not analysed, the problem of propagation of a sonic boom is merely geometrical problem.

This paper prasents the analitic method of determination of a wavefront and application of that to the following models of an atmosphere: 1/still honogeneous atmosphere,2/still atnosphere with gradient of sound velocity,3/still atnosphere with temperature gradient,4/homogeneous atmosphere with vertical wind velocity distribution and 5/atmosphere with gradient of sound velocity and vertical wind velocity distribution.

## I.Introduction

Sonic boom is caused by the shock waves occurring when an aircrait /rocket,projectile/ plies at the supersonic speed.As it is well known, sonic boom may be a danger to the other aircrait in the air and to the people and objects on the ground. In order to determine the range of a sonic boon it is necessary to know how do the shock waves propagate. Propagation of the shock waves depends on the history of a flight and atmospheric conditions,mainly on the temperature gradient and wind velocity distribution.

General theory of a sonic boon is presented in paper of Tarren and Randall ${ }^{(1)}$. In this theory there are intıoduced the notions
of a waveiront and rays. The ray may be treated as a path of element of a wavefront. Influence of temperature gradient on propagation of a sonic boon was investigated in above nentioned paper,in another paper of Warren ${ }^{(2)}$ and by author of present paper ${ }^{(3),(4)}$ as well. Influence of wind velocity was considered by Dressler and Fredholm ${ }^{(5)}$.

The aim of the present paper is the investigation of influence of temperature gradient and vertical wind velocity distribution on propagation of a sonic boom. It is assumed that a flight path lies in the vertical plane that is parallel to the vector of wind velocity.propacation of a sonic boom is considered merely in the plane of a flight path. Intensity of a sonic boom is not analysed.

## II. Symbols

a -sound velocity
$a_{A}$-value of a at altitude of aircraft
$\overline{\mathrm{a}}=\mathrm{a} / \mathrm{a}_{\mathrm{A}}$
k -non-dimensional coefficient /Table 1/
1 -coefficient /Table 1/
t -time
$\overline{\mathrm{E}}$-non-dimensional time/Table 1/
$t_{A}$-time corresponding to the certain po-
${ }^{\text {A }}$ sition of an aircraft
$\mathrm{w}=\mathrm{w}_{\mathrm{G}}{ }^{-\mathrm{w}} \mathrm{A}$
$\mathrm{w}_{\mathrm{A}}$-value of $\mathrm{w}_{\mathrm{G}}$ corresponding to the altitude of aircraft
$w_{G}$-wind velocity relative to the ground $\overline{\mathrm{w}}=\mathrm{w} / \mathrm{a}_{\mathrm{A}}$
$x, y$-Cartesian coordinates moving at the speed $\mathrm{w}_{\mathrm{A}}$ relative to the ground
$\overline{\mathrm{x}}, \overline{\mathrm{y}}$-non-dimensional coordinates /Table 1/ $x_{A}$-horizontal coordinate of an aircraft $x_{G}$-horizontal axis connected with the ground
$C=1 / \sin \left(\alpha_{\mp} \Gamma\right)$, where upper and lower signs apply to the regions, respectively,above and under a flight path
$H$-altitude of an aircrait
$\mathrm{H}_{\mathrm{O}}$-altitude of an atmosphere with temperature gradient /Table 1/
$M=U / a_{A}$-Mach number of an aircraft
U -flight speed relative to the air
V -normal velocity of a wavefront that is measured in $x, y$-coordinates
$\alpha=\operatorname{arc} \sin 1 / \mathrm{M}-$ Mach angle
$\varepsilon= \pm 1$, where upper and lower signs apply, respectively, to the aft- and headwind $\Gamma$-angle of climb
$\varphi$-angle between normal to the wavefront and x -axis
$\psi$-angle between tangent to the ray and x -axis
$\Psi_{A}$-value of $\psi$ corresponding to the altitude of an aircraft

## III.Assumptions

In atnosphere there is a vertical temperature gradient,i.e. $a=a / y /$ and vertical wind velocity distribution,i.e. $\mathrm{w}_{\mathrm{G}}=$ $=w_{G} / y /$. The value of ${ }_{W}{ }_{G}$ at altitude of an aircraft is equal to $\mathrm{w}_{\mathrm{A}}$. The flight path lies in the vertical plane $/ \mathrm{x}, \mathrm{y} /$, x -axis is horizontal and moves at the speed $w_{A}$ relative to the ground. In $x, y$-coordinates the wind velocity is equal to $w / y /=w_{G} / y /-$ $-w_{A}$. Vector of wind velocity lies in $/ x, y /-$ plane.

At the instant $t_{A}$ an aircraft is at the point $/ x_{A}, 0 /$,its Wach number is equal to $M \geqslant 1$, Nach ang le $\alpha$, altitude $H$ and angle of climb $\Gamma$.According to the definition of a ray, at the point $/ x_{A}, 0 /$ the angle between the tangents to a ray and a plight path is equal to $/ \frac{\pi}{2}-\alpha /$, the angle between the tangent to a ray and $x$-axis is equal to /Figure 1/

$$
\begin{equation*}
\psi_{A}= \pm\left[\frac{\pi}{2}-(\alpha \mp \Gamma)\right] \tag{1}
\end{equation*}
$$

Where the upper and lower signs apply to the wavefronts proparating, respectively,
above and under the tangent to a flight path.


FIGURE 1.

IV.General Snell's Law

Let us consider Figure 2. The normal ve_ locity of a wavefront measured in $x, y-c o-$ ordinates is equal to

$$
\begin{equation*}
v=a+w \cos \varphi \tag{2}
\end{equation*}
$$

One exists the relation between $V$ and $\varphi^{(5)}$. After suitable nodifications this relation may be expressed in the form

$$
\begin{equation*}
\mathrm{V} / \cos \varphi=\mathrm{const} \tag{3}
\end{equation*}
$$

and that is fulfilled along a ray.Substituting (2) to (3) and calculating the constant from the condition that at the beginning of a ray there is $\mathrm{w}=0, \mathrm{a}=0$ and $\varphi=\psi=\psi_{A}$, we get the following formula that will be called the general Snell's law

$$
\begin{equation*}
a / \cos \varphi+w=a_{A} / \cos \psi_{A} \tag{4}
\end{equation*}
$$

where $\Psi_{A}$ is determined by (1). The rays are not orthogonal to the wavefront and they are the segments of space lines.Two rays for that the angle $\Psi_{\mathrm{A}}$ lies in $/ x, y /-$ plane are the segments of plane lines; these rays will be called, respectively, upper and lower ray /Figure $1 /$.

If $\mathrm{w}=0$, then formula (4) takes the form of ordinary Snell's law
$a / \cos \psi=a_{A} / \cos \psi_{A}$



FIGURE 2.


FIGURE 3

## V.Method of Determination

of a Wavefront

In $/ x, y, t /-s p a c e ~ t h e ~ p a t h ~ o f ~ e l e m e n t ~ o f ~$ a wavefront is the segment of line going through the point $/ x_{A}, 0, t_{A} /$ Projection of this segment into $/ x, y /-p l a n e$ is called a ray,projection into $/ \mathrm{y}, \mathrm{t} /-\mathrm{plane}$ will be called a path of a wavefront in $/ \mathrm{y}, \mathrm{t} /-\mathrm{pla}-$ ne.

It is seen from Figure 2 that along a ray the following relations are satisfied

$$
\begin{align*}
& d x=a(\cos \varphi+w) d t  \tag{5}\\
& d y=a \sin \varphi d t \tag{6}
\end{align*}
$$

Eliminating from (5) and (6) by means of (4) the angle $\varphi$, we obtain differential equation of rays

$$
\begin{equation*}
d y / d x=f(x, y) \tag{7}
\end{equation*}
$$

and differential equation of paths of a wavefront in $/ \mathrm{y}, \mathrm{t} /-\mathrm{plane}$

$$
\begin{equation*}
d \mathbf{y} / \mathrm{dt}=\mathrm{g}(\mathbf{y}, \mathrm{t}) \tag{8}
\end{equation*}
$$

Let us assume that the solutions of (7) and (8) are known. Considering the ray emanating at the time $t_{A}$ from the point $/ x_{A}, 0 /$, we can determine by means of solutions of (7) and (8) the coordinates $x, y$ of any point of a wavefront at any instant $t>t_{A} /$ Figure $3 /$. Let $x_{G}$ denotes the horizontal axis connected with the ground. At every instant $t>t_{A}$ the coordinate $x_{G}$ of a wavefront propagating along a ray emanating at the instant $t_{A}$ at the point $/ x_{A}, 0 /$, expresses as follows

$$
x_{G}=x+w_{A}\left(t-t_{A}\right)
$$

where $x$ is determined by means of solutions of (7) and (8).This procedure is shown in Figure 3.

## VI. Parametric Equations of the Path of Element of a Wavefrant

In order to find the solutions of (7) and (8), we shall derive the parametric /parameter $\varphi=-\pi / 2 \div \pi / 2 /$ equations of the path in $/ x, y, t /-$ space of element of a wavefront. These equations will be in the forms

$$
\begin{align*}
& x=x(\varphi)  \tag{9}\\
& y=y(\varphi)  \tag{10}\\
& t=t(\varphi) \tag{11}
\end{align*}
$$

The expressions (9) and (10) are parametric equations of a ray and they satisfy the differential equation of rays (7); the expressions (10) and (11) are parametric equations of the path of a wavefront in $/ \mathrm{y}, \mathrm{t} /-\mathrm{plane}$ and satisfy (8).

Resolving (4) with respect to $y$,we get immediately the parametric equation (10) of coordinate $y$.Differentiating (10) with respect to $\varphi$,we receive the following expression

$$
\mathrm{d} y / \mathrm{d} \varphi=\mathrm{y}^{\prime}(\varphi)
$$

By means of (6), (10) and ( $10^{\prime}$ ) we obtain the relation

$$
\begin{equation*}
d t / d \varphi=y^{\prime}(\varphi) / a(\varphi) \sin \varphi \tag{11}
\end{equation*}
$$

and by means of (5), (10) and (11)-the relation

$$
\mathrm{dx} / \mathrm{d} \varphi=\mathrm{y}^{\prime}(\varphi)[\operatorname{ctg} \varphi+\mathrm{w}(\varphi) / \mathrm{a}(\varphi) \sin \varphi]
$$

The expressions $\left(9^{\prime}\right),\left(10^{\prime}\right),\left(11^{\prime}\right)$ will be called the differential equations of coordinates of the path of a wavefront. Integrating ( $9^{\prime}$ ) and ( $11^{\prime}$ ), we get the parametric equations of coordinate $x$ and $t$ of the path of a wavefront.

## VII. Parametric Equations of a Wave-

front in Straight Level Flight at Constant Mach Number

In this case of flight we shall derive directly the paranetric equations of a wavefront in the forms

$$
\begin{align*}
& \mathrm{x}=\mathrm{x}_{1}(\varphi)  \tag{12}\\
& \mathrm{y}=\mathrm{y}(\varphi) \tag{10}
\end{align*}
$$

Parametric equation of coordinate $y$ is identical as in previous heading. With regard to the wavefront the following condition is fulfilled

$$
\begin{equation*}
d y / d x=-\operatorname{ctg} \varphi \tag{13}
\end{equation*}
$$

Talcing into account ( $10^{\prime}$ ), we obtain from (13) the differential equation of coordinate $x$ of a wavefront

$$
\mathrm{dx} / \mathrm{d} \varphi=-\mathrm{y}^{\prime}(\varphi) \mathrm{tg} \varphi
$$

and after integrating-the parametric equation (12) of coordinate $x$ of a wavefront. By means of (4) and (13) we derive the differential equation of wavefronts

$$
\begin{equation*}
\mathrm{dy} / \mathrm{dx}=\mathrm{h}(\mathrm{x}, \mathrm{y}) \tag{14}
\end{equation*}
$$

Parametric equations (10) and (12) of coordinates of a waveiront satisfy the differential equation (14).

It should be noticed that the wavefront described by (10) and (12) noves at the speed $w_{A}$ relative to the ground.

## VIII.Models of an Atmosphere

The nethod oi detemination of a FavePront described in the headings $V, V /$ and $V I I$, will be applied to the following inodels of an atmosphere:
$1 /$ still homogeneous atmosphere $-\mathrm{a}=$ const, $\mathrm{w}_{\mathrm{G}}=0$
$2 /$ still atmosphere with gradient of so- assume the notation und velocity
$a=a_{A}\left[1-y /\left(H_{0}-I\right)\right], \quad w_{G}=0$

3/still atmosphere with temperature gradient
$\mathrm{a}=\mathrm{a}_{\mathrm{A}}\left[1-\mathrm{y} /\left(\mathrm{H}_{0}-\mathrm{H}\right)\right]^{1 / 2}, \quad \mathrm{w}_{\mathrm{G}}=0$

4/homogeneous atmosphere with vertical wind velocity distribution
$\mathrm{a}=$ const, $\mathrm{w}_{\mathrm{G}}=\varepsilon \mathrm{a}(\mathrm{y}+\mathrm{H}) / 1, \mathrm{w}=\varepsilon \mathrm{ay} / 1$

5/atmosphere with gradient oi sound velocity and vertical wind velocity distribution
$a=a_{A}\left[1-y /\left(H_{0}-H\right)\right]$
${ }_{W}=\varepsilon a_{A} k(y+H) /\left(\mathrm{H}_{\mathrm{O}}-\mathrm{H}\right), \mathrm{w}=\varepsilon a_{A} k y /\left(\mathrm{H}_{\mathrm{O}}-\mathrm{H}\right)$

## IX. Propagation of a Sonic Boom

With regard to the models $2,3,4,5$ oi an atmosphere it will be introduced non-dimensional quantities: coordinates $\bar{x}, \bar{y} ;$ time $\bar{t}$, sound velocity $\bar{a}$, wind velocity $\bar{w}$; their scales are tabulated in Table 1. Ve shall

| 열 | $\overline{\mathbf{x}}$ | $\overline{\mathbf{y}}$ | $\bar{t}$ | $\overline{\mathbf{a}}$ | - |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | x | y | t | a | 0 |
| 2 | $\frac{x}{H_{0}-\mathrm{H}}$ | $\frac{y}{H_{0}-\mathrm{H}}$ | $\frac{a_{A} t}{H_{0}-H}$ | 1- $\overline{\mathbf{y}}$ | 0 |
| 3 | $\frac{x}{H_{0}^{-H}}$ | $\frac{y}{H_{0}-\mathbf{H}}$ | $\frac{a_{A} t}{H_{0}-\mathbf{H}}$ | $(1-\bar{y})^{1 / 2}$ | 0 |
| 4 | $\stackrel{x}{1}_{(1>0)}^{1}$ | $\frac{\mathrm{y}}{1}$ | $\frac{a t}{1}$ | 1 | $\varepsilon \overline{\mathbf{y}}$ |
| 5 | $\frac{\mathrm{x}}{\mathrm{H}_{0}-\mathrm{H}}$ | $\frac{y}{H_{0}-\mathbf{H}}$ | $\frac{a_{A} t}{H_{0}-\mathbf{H}}$ | 1- $\overline{\mathbf{y}}$ | $\begin{array}{\|c\|} \varepsilon k \bar{y} \\ (0<k \leqslant 1) \end{array}$ |

TABLE 1.

$$
\begin{equation*}
C=1 / \sin (\alpha \mp \Gamma) \tag{15}
\end{equation*}
$$

where upper and lower signs apply, respectively, to the upper and lower ray.

In Table 2 there are tabulated the differential equations of rays ( 7 ), paths of a wavefront in $/ \mathrm{y}, \mathrm{t} /-\mathrm{plane}$ (8) and wavefronts (14).Equations (7) and (8) correspond to any flight, quantity $C$ defined by (15) may change along a plight path.

In the case of model 1 of an atmosphere the equation (14) corresponds to the straight flight at constant Mach number and there is $C=$ const along a flight path. For models $2,3,4,5$ the equation (14) corresponds to the straight level flight at constant Mach number and $C=M=$ const along a plight path.

In Table 3 there are represented the differential equations $\left(9^{\prime}\right),\left(10^{\prime}\right),\left(11^{\prime}\right)$ and

|  | DIFFERENTIAL EQUATIONS OF |  |  |
| :---: | :---: | :---: | :---: |
|  | $\begin{array}{rl}\text { R A } \\ \mathrm{Y} & \mathbf{S} \\ \mathrm{d} / \mathrm{y} \overline{\mathrm{x}} & = \\ \end{array}$ | $\begin{gathered} \text { PATHS_OF A TAVRPRONT } \\ \text { IN }(\bar{y}, \bar{t})-\text { PLANTS } \\ \mathrm{d} \overline{\mathrm{y}} / \mathrm{d} \overline{\mathrm{t}}= \pm \end{gathered}$ | $\begin{gathered} \text { WAVEPMONYS } \\ \text { (C=CONSY, M}=\text { CONST }) \\ \mathrm{d} \overline{\mathrm{y}} / \mathrm{d} \overline{\mathrm{z}}=\mp \end{gathered}$ |
| 1 | $\left(c^{2}-1\right)^{1 / 2}$ | $a\left(1-\frac{1}{c^{2}}\right)^{1 / 2}$ | $\left(c^{2}-1\right)^{-1 / 2}$ |
| 2 | $\left[\frac{c^{2}}{(1-\bar{y})^{2}}-1\right]^{1 / 2}$ | $(1-\bar{y})\left[1-\frac{(1-\bar{y})^{2}}{c^{2}}\right]^{1 / 2}$ | $\left[\frac{x^{2}}{(1-\bar{y})^{2}}-1\right]^{-1 / 2}$ |
| 3 | $\left(\frac{c^{2}}{1-\bar{y}}-1\right)^{1 / 2}$ | $\left[(1-\bar{y})\left(1-\frac{1-\bar{y}}{c^{2}}\right)\right]^{1 / 2}$ | $\left[\frac{x^{2}}{1-y}-1\right]^{-1 / 2}$ |
| 4 | $\frac{\left[(c-\varepsilon \overline{\mathbf{y}})^{2}-1\right]^{1 / 2}}{\varepsilon \overline{\mathbf{y}}(c-\varepsilon \overline{\mathbf{y}})+1}$ | $\left[1-\frac{1}{(c-\varepsilon \bar{y})^{2}}\right]^{1 / 2}$ | $\left[(M-\varepsilon \bar{y})^{2}-1\right]^{-1 / 2}$ |
| 5 | $\frac{(1-\bar{y})\left[(c-\varepsilon k \bar{y})^{2}-(1-\overline{\mathbf{y}})^{2}\right] 1 / 2}{(1-\bar{y})^{2}+\varepsilon k \bar{y}(c-\varepsilon k \bar{y})}$ | $(1-\bar{y})\left[1-\frac{(1-\bar{y})^{2}}{(C-\varepsilon k \bar{y})^{2}}\right]^{1 / 2}$ | $\left[\frac{(m-\varepsilon k \bar{y})^{2}}{(1-\bar{y})^{2}}-1\right]^{-1 / 2}$ |

TABLE 2.

|  | DIFFERENTIAL EQUATIONS OF COORDINAPRS OF <br> PATH OF A WAVEPRONT <br> TAVEFRONT ( $\mathbf{M}=$ CONST) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\mathrm{d} \overline{\mathrm{x}} / \mathrm{d} \varphi=$ | $\mathrm{d} \overline{\mathbf{y}} / \mathrm{d} \varphi=$ | $\mathrm{d} \overline{\mathbf{t}} / \mathrm{d} \varphi=$ | $\mathrm{d} \overline{\mathrm{x}} / \mathrm{d} \varphi=$ | $d \bar{y} / \mathrm{d} \varphi=$ |
| 2 | C $\cos \varphi$ | C $\sin \varphi$ | 1/008 4 | $-\operatorname{Msin}^{2} \varphi / 008 \varphi$ | $M \sin \varphi$ |
| 3 | $2 \mathrm{C}^{2} 20 \mathrm{~s}^{2} \varphi$ | $c^{2} \sin 2 \varphi$ | 2 C | $-2 M^{2} \sin ^{2} \varphi$ | $M^{2} \sin 2 \varphi$ |
| 4 | $\varepsilon\left(\sin ^{2} \varphi-\operatorname{coss} \varphi\right) / 003^{3} \varphi$ | $-\delta \sin \varphi / 00 s^{2} \varphi$ | $-\varepsilon / \cos ^{2} \varphi$ | $-\sin ^{2} \varphi / \cos ^{3} \varphi$ | $-\varepsilon \sin \varphi / \cos ^{2} \varphi$ |
| 5 | $\frac{\varepsilon k\left(\sin ^{2} \varphi-\cos \varphi\right)+C \cos ^{2} \varphi}{\cos \varphi(1-\varepsilon \cos \varphi)^{2}}$ | $\frac{(c-\varepsilon k) \sin \varphi}{(1-\varepsilon \cos \varphi)^{2}}$ | $\frac{1}{\cos \varphi(1-\varepsilon k \cos \varphi)}$ | $\frac{(M-\varepsilon k) \sin ^{2} \varphi}{\cos \varphi(1-\varepsilon k 0 e s \varphi)^{2}}$ | $\frac{(M-\varepsilon k) \sin \varphi}{(1-\varepsilon k 00 s \varphi)^{2}}$ |

table 3.

|  |  SOLUTIONS OF DIFFERENTIAL EQUATIONS OF <br> R Y S PATHS OFA WAVEPRONT IN $(\overline{\mathrm{y}}, \overline{\mathrm{t}})$ - PLANE |  |  |  | WAVEFRONTS (CmCONST, MmCONST) |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | PARAMETRICAL SOLUTIONS | OTHER SOLUTIONS | PARAMETRICAL SOLJTIONS | OTHEA SOUTTIONS | $\begin{aligned} & \text { PARAMEYRICAL } \\ & \text { SOLUTIONS } \end{aligned}$ | $\begin{gathered} \text { OTHER } \\ \text { SOLUYTONS } \end{gathered}$ |
| 1 |  | $y= \pm\left(c^{2}-1\right)^{1 / 2} x$ <br> STRAIGET LINE |  | $y= \pm a\left(1-\frac{1}{c^{2}}\right)^{1 / 2} t$ <br> STRAIGHT LINE |  | $\begin{aligned} & y=-\left(c^{2}-1\right)^{-1 / 2} x \\ & \text { STRUGHT LTNE } \end{aligned}$ |
| 2 | $\begin{aligned} & \overline{\mathbf{x}}=\operatorname{csin} \varphi \\ & \overline{\mathbf{y}}=1-\operatorname{coc} \varphi \end{aligned}$ <br> CRCLE | $\overrightarrow{\mathbf{x}}$ $=0$ <br> WHEN $\quad \mathbf{C}$ $=\infty$ <br> STRAIGHT LINE  | $\begin{aligned} & \bar{t}=\ln \operatorname{tg}\left(\frac{\pi}{4}+\frac{\varphi}{2}\right) \\ & \bar{y}=1-\cos \varphi \end{aligned}$ | $\begin{aligned} & \bar{t}=\overline{+} \ln (1-\bar{y}) \\ & \text { WHEN } \quad C=\infty \end{aligned}$ | $\begin{aligned} & \bar{x}=M\left[\sin \varphi-\ln \operatorname{tg}\left(\frac{\pi}{4}+\frac{\varphi}{2}\right)\right] \\ & \bar{y}=1-\operatorname{Moos} \varphi \end{aligned}$ <br> TRACTRIX | $\begin{aligned} \overline{\mathbf{y}} & =0 \\ \text { WHEN } \quad \mathbf{M} & =\infty \end{aligned}$ <br> STRAIGET LINE |
| 3 | $\begin{aligned} & \bar{x}=\frac{c^{2}}{2}(2 \varphi+\sin 2 \varphi) \\ & \bar{y}=1-c^{2} \cos ^{2} \varphi \end{aligned}$ CYCLOID | $\qquad \overline{\mathbf{x}}$ $=0$ <br> WHEN $\quad \mathbf{C}$ $=\infty$ <br> STRAIGHT LINE  | $\begin{aligned} & \bar{t}=2 C \varphi \\ & \bar{y}=1-c^{2} \cos ^{2} \varphi \end{aligned}$ | $\bar{t}=-2(1-\bar{y})^{1 / 2}$ <br> WHEN $C=\infty$ PARABOLA | $\begin{aligned} & \bar{x}=\frac{M^{2}}{2}(\sin 2 \varphi-2 \varphi) \\ & \bar{y}=1-M^{2} \cos ^{2} \varphi \end{aligned}$ <br> CYCLOID | $\overline{\mathbf{y}}$ $=0$ <br> WHEN $\quad \mathbf{M}$ $=\infty$ <br> STRAIGHT LINE  |
| 4 | $\begin{aligned} & \overline{\bar{x}=}=\frac{\varepsilon}{2}\left[\operatorname{tg} \varphi\left(\frac{1}{008 \varphi}-2 C\right)-\right. \\ &\left.\operatorname{lntg}\left(\frac{\pi}{4}+\frac{\varphi}{2}\right)\right] \\ & \bar{y}= \varepsilon\left(c-\frac{1}{\cos \varphi}\right) \end{aligned}$ | $\begin{aligned} & \qquad \overline{\mathrm{x}}= \pm \overline{\mathbf{y}}^{2} / 2 \\ & \text { WHEN } \quad \mathrm{C}=\infty \\ & \text { PARABOLA } \end{aligned}$ | $\begin{aligned} & \bar{t}=-\varepsilon \operatorname{tg} \varphi \\ & \bar{y}=\varepsilon\left(c-\frac{1}{\cos \varphi}\right) \end{aligned}$ | $\overline{\mathbf{y}}= \pm \overline{\mathbf{t}}$ <br> WHEN $\quad \mathbf{C}=\infty$ <br> STRAIGHT LINE | $\begin{aligned} & \overline{\mathrm{x}}=\frac{\varepsilon}{2}\left[\frac{\sin \varphi}{\cos ^{2} \varphi}-\operatorname{lntg}\left(\frac{\pi}{4}+\frac{\varphi}{2}\right)\right] \\ & \overline{\mathrm{y}}=\varepsilon\left(M-\frac{1}{\cos \varphi}\right) \end{aligned}$ | $\overline{\mathbf{y}}=0$ WHEN $\mathbf{M}=\infty$ STRAIGHT LINE |
| 5 $(k=1)$ | $\begin{aligned} \overline{\mathrm{x}}= & (\operatorname{c-2\varepsilon }) \operatorname{tg}\left[\frac{\pi}{4}(1+\varepsilon)-\frac{\varepsilon \varphi}{2}\right]+ \\ & \varepsilon \operatorname{lntg}\left(\frac{\pi}{4}+\frac{\varphi}{2}\right) \\ \bar{y}= & \frac{1-\cos \varphi}{1-\varepsilon \cos \varphi} \end{aligned}$ | $\begin{aligned} & \bar{y}=0 \quad \text { WHEN } \\ & \mathbf{c}=1 \text { AND } \varepsilon=1 \end{aligned}$ <br> STRAIGHT LINE; $\bar{x}=\overline{+}[\bar{y}+\ln (1-\bar{y})]$ <br> WHEN $C=\infty$ | $\begin{aligned} & \bar{t}=\operatorname{lntg}\left(\frac{\pi}{4}+\frac{\varphi}{2}\right)- \\ & t g\left[\frac{\pi}{4}(1+\varepsilon)-\frac{\varepsilon \varphi}{2}\right] \\ & \bar{y}=\frac{1-\cos \varphi}{1-\varepsilon \cos \varphi} \end{aligned}$ | $\overline{\mathbf{y}}=0 \quad$ WHEN <br> $C=1$ AND $\varepsilon=1$ <br> STRAIGHT LINE; $\bar{t}=\overline{+} \ln (1-\bar{y})$ <br> WHEN $\quad \mathbf{C}=\infty$ | $\begin{aligned} \bar{x}= & (M-\varepsilon)\left\{2 \operatorname{tg}\left[\frac{\pi}{4}(1+\varepsilon)-\frac{\varepsilon u^{\top}}{2}\right]\right. \\ & \left.-\operatorname{lntg}\left(\frac{\pi}{4}+\frac{\varphi}{2}\right)\right\} \\ \bar{y}= & \frac{1-\cos \varphi}{1-\varepsilon \cos \varphi} \end{aligned}$ | $\begin{array}{ll} \overline{\mathbf{x}}=0 & \text { WHEN } \\ \mathbf{M}=1 \text { AND } & \varepsilon=1 \\ \text { STBAIGHT } & \text { LINE; } \\ & \overline{\mathbf{y}}=0 \\ \text { WHEN } & \mathbf{M}=\infty \\ \text { STRAIGHT } & \text { LINE } \end{array}$ |

(12') of coordinates of the path of a wavefront and coordinates of a wavefront $/ C=M$ const along a flight path/.In Table 4 there are tabulated the solutions of differential equations (7), (8) and (14).In the case of model 5 of an atmosphere one can obtain the parametric /parameter $\varphi$ / solutions merely for $k \leqslant 1$. In Table 4 there are represented the parametric solutions for $\mathrm{k}=1$.

In Table 5 that concerns the model 1 of


TABLE 5.

| op diprgasmilal |  |  |  |
| :---: | :---: | :---: | :---: |
|  | Atwospraze 2 | ATMOSRRER 3 | atosprabes 4, $\varepsilon$ - 1 |
|  |  |  |  |
|  |  |  |  |
|  |  |  |  |

table 6.


## TABLE 7.

## X.References

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table 8.

TABLE 9.




TABLE 13.

